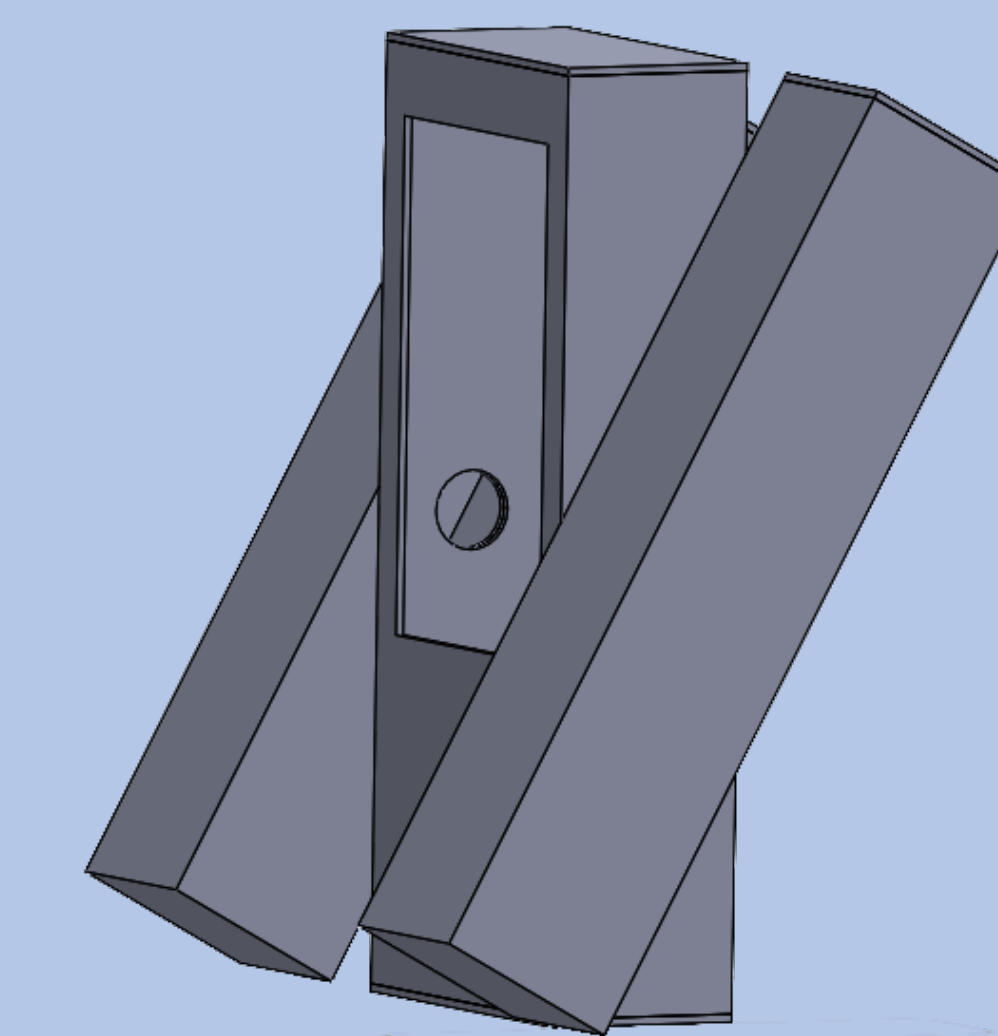




# D.A.M.E.

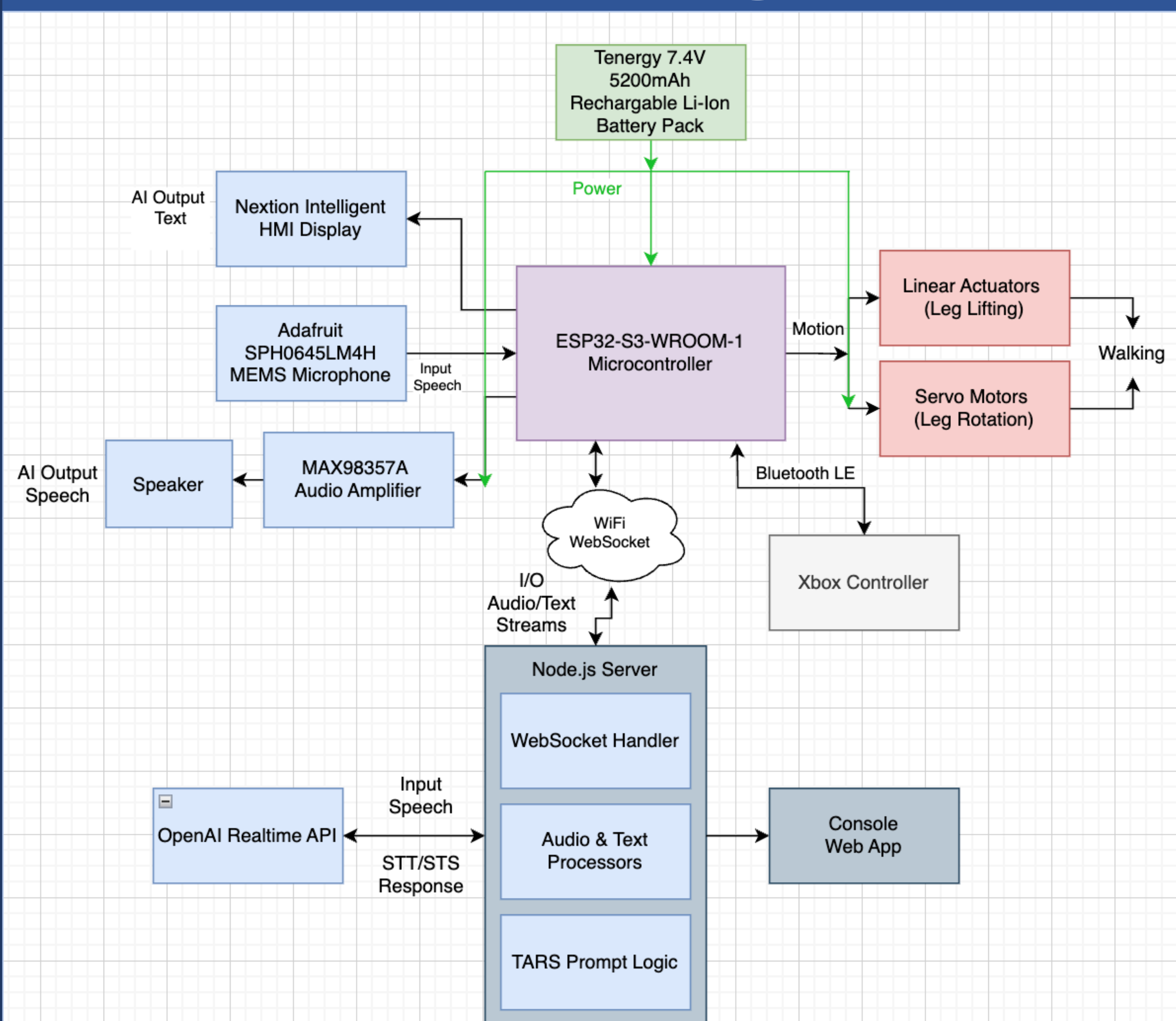
Dynamic Artificial Mechanical Entity



## Overview

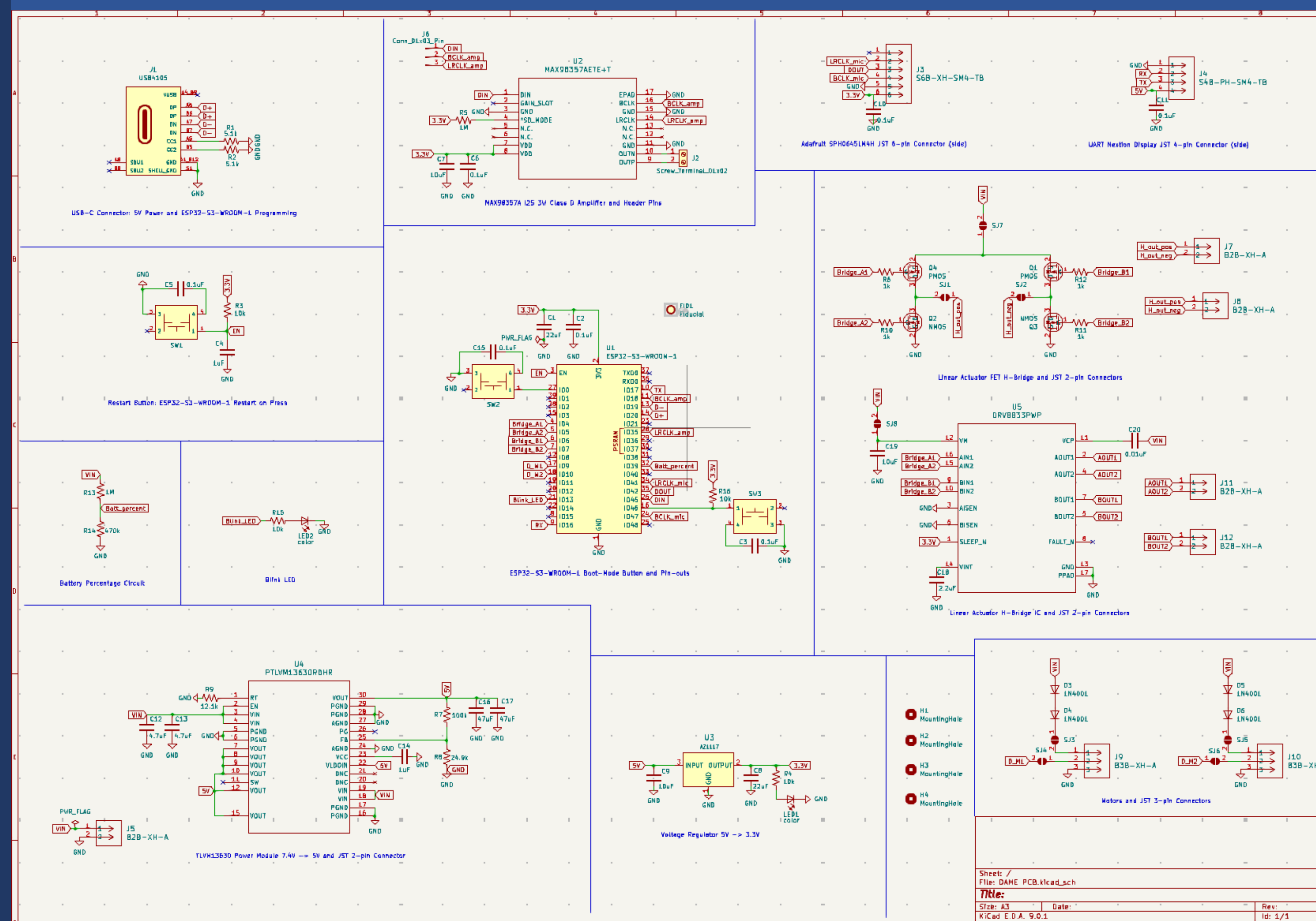
*Interstellar* captured the minds of young engineers in 2014, but what happens when those kids grow up? They build the robot from the movie 11 years later. Our **Dynamic Artificial Mechanical Entity**, DAME, walks and talks with a snappy persona akin to that of the movie's robot. With a fully embedded AI interface, DAME is capable of full conversations!

## Block Diagram



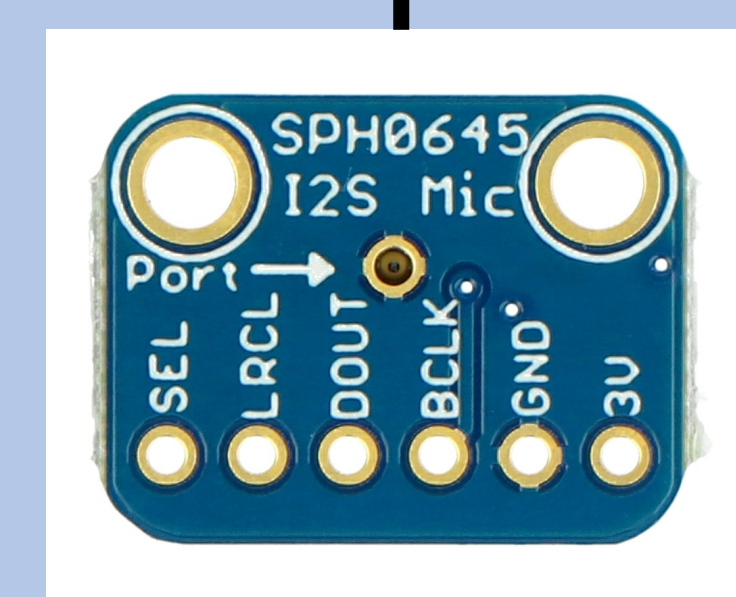
DAME Team: Jack Corrao, Jack McGarrity, Matthew Sims, Xander Steele, and Garrett Young

## Board Schematic

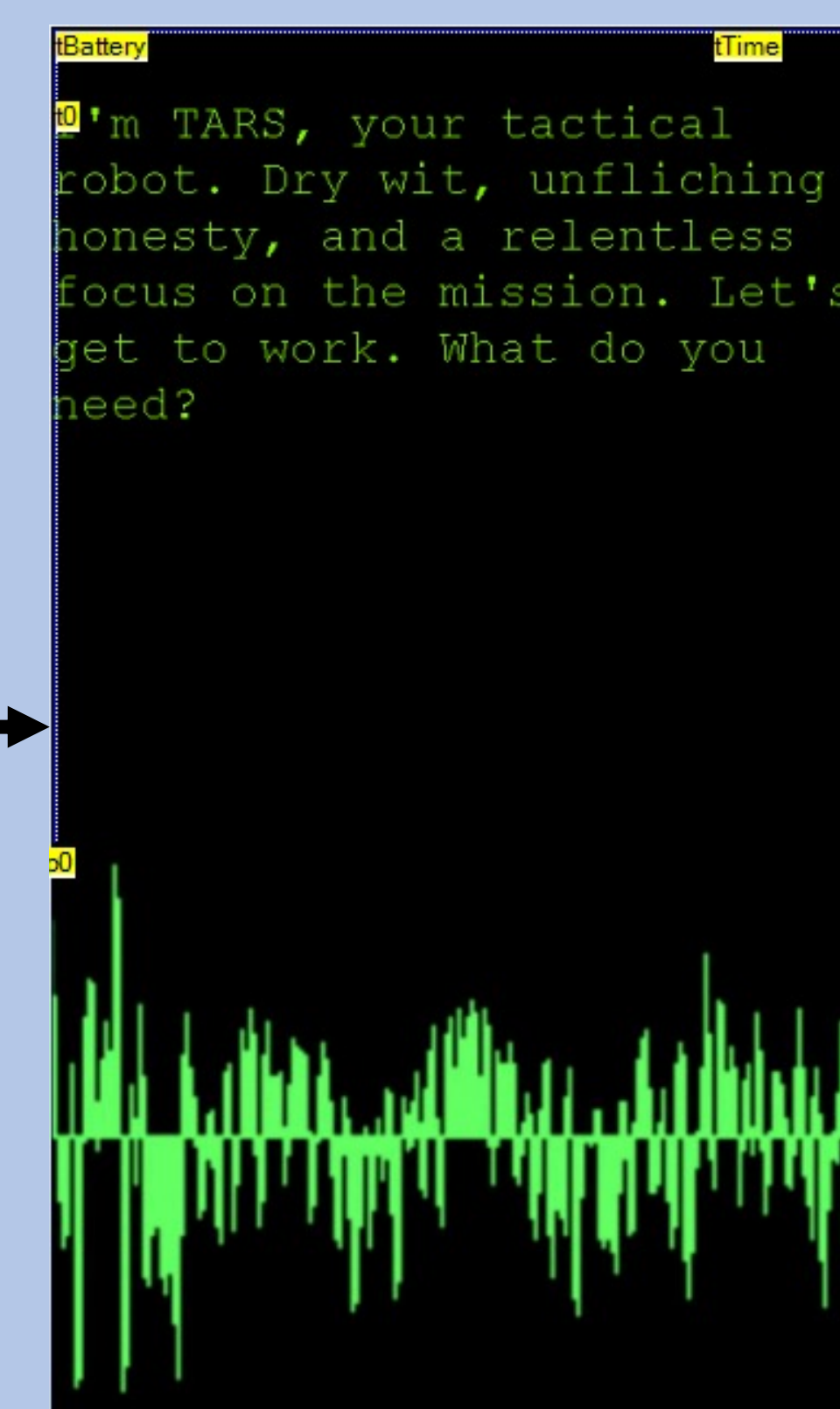


## User Interface

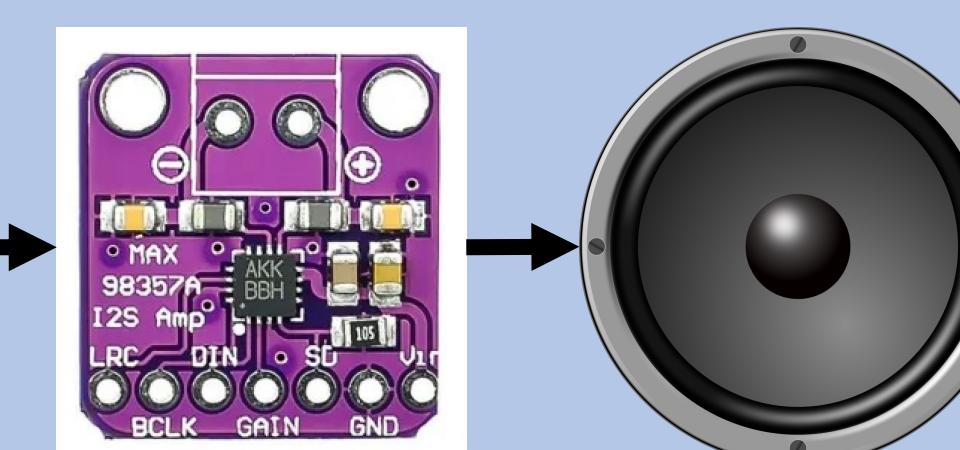
### Xbox Controller



SPH0645LM4H Microphone



Nextion Screen



MAX98357A Speaker Amplifier

## Key Features

### Mobility:

- **DC House 1.2" Linear Actuator** for linear arm motion
- **DS04-NFC** for arm rotation motion
- **PMOS/NMOS H-Bridge** for reversing linear polarity

### Frame:

- **10" x 12"** DAME frame 3D-printed from the EIH
- **Six unique parts**: lower body, upper body, 2x body cap, 2x lower arm, 2x upper arm, 2x arm cap
- Each upper and lower portion of the frame is **mounted** with screws and glue, **flush** with the conjoined piece

### Artificial Intelligence:

- Real-time voice interaction through **OpenAI GPT- 4o**
- **WebSocket server** handles bidirectional audio/text streams
- Uses **LangChain** tools to execute commands
- Natural, **dry-witted TARS personality** driven by custom GPT prompt
- **Audio chunking + buffering** to support ESP32 constraints
- **Prioritized audio/text queuing** ensures smooth voice playback without interruption
- Entire server stack built with **TypeScript + Hono framework**

### User-Interface:

- **ESP32-S3-WROOM-1** manages local interaction and peripherals
- **I2S microphone and speaker** for real-time voice capture/playback
- **Xbox Series X controller** triggers voice recording and movement
- **Nextion 7" touchscreen** shows live transcription from GPT
- Modular C++ firmware using **PlatformIO + Arduino Framework**